

# A tiny bit of Analysis

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Riemann integral

Metric spaces, contraction maps

Differentiating under the integral

Picard's theorem for O.D.E.

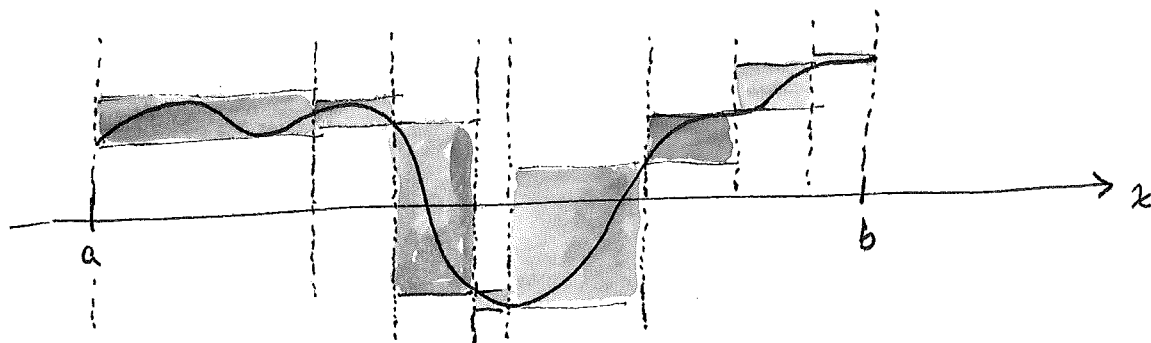
# The Riemann Integral

$f: [a, b] \rightarrow \mathbb{R}$  continuous

Let  $\Pi$  be the directed set of partitions of  $[a, b]$ , ordered by inclusion. Let

$$\Pi \xrightarrow{K} \mathbb{R} \times \mathbb{R}$$

be the net defined by  $K(\pi) \equiv \sum_{[l, h] \in \pi} (h-l) \cdot f[l, h]$ .



Since  $f$  is continuous,  $K$  is contained in a compact subset of  $\mathbb{R} \times \mathbb{R}$ . By Gersch THEOREM 35,  $K$  has a point of accumulation  $[\min, \max] \in \mathbb{R} \times \mathbb{R}$ .

Since  $K$  is also order preserving,  $[\min, \max]$  is also the limit of  $K$  ( $\mathbb{R} \times \mathbb{R}$  ordered by containment).

If  $\min \neq \max$ , a finer partition will make  $\min$  and  $\max$  closer. Thus  $\min = \max \equiv \int_a^b f(x) dx$ .

I also want to claim (with a proof)

that

$$\int_a^b (f(x) + g(x)) dx = \int_a^b f(x) dx + \int_a^b g(x) dx$$

and if  $f(x, y)$  is continuous on  $\mathbb{R}^2 \rightarrow \mathbb{R}$ ,

then

$$\int_a^b f(x, y) dx : \mathbb{R} \rightarrow \mathbb{R}$$

is also continuous.

Differentiating under the integral (Used in the Euler-Lagrange equation handout).

$$\frac{d}{dy} \int_a^b f(x, y) dx \stackrel{?}{=} \int_a^b \frac{\partial f}{\partial y}(x, y) dx$$

Suppose  $\frac{\partial f}{\partial y}$  exists. Then

$$F(x, y, \lambda) \equiv \begin{cases} \frac{f(x, y + \lambda) - f(x, y)}{\lambda} & \text{if } \lambda \neq 0 \\ \frac{\partial f}{\partial y}(x, y) & \text{if } \lambda = 0 \end{cases}$$

is continuous.  $\Rightarrow$

$$\int_a^b F(x, y, \lambda) dx = \begin{cases} \frac{\int_a^b f(x, y + \lambda) dx - \int_a^b f(x, y) dx}{\lambda} & \text{if } \lambda \neq 0 \\ \int_a^b \frac{\partial f}{\partial y}(x, y) dx & \text{if } \lambda = 0 \end{cases}$$

$$\text{is continuous } \Rightarrow \frac{d}{dy} \int_a^b f(x, y) dx = \int_a^b \frac{\partial f}{\partial y}(x, y) dx \quad \text{Q.E.D.}$$

# Cauchy Sequences in a Metric Space

... are defined just as we did in "Numbers"

def: A sequence  $r_1, r_2, r_3, \dots$  in a metric space is Cauchy if  $d(r_i, r_j)$  remains below any chosen  $\epsilon > 0$  for all  $i, j$  greater than some  $N$ .

def: A metric space is complete if every Cauchy sequence converges to a limit.

Factoid: Suppose

$$r_1, r_2, r_3, r_4, \dots$$

$$\begin{array}{cccc} \longleftrightarrow & \longleftrightarrow & \longleftrightarrow & \longleftrightarrow \\ \delta_1 & \delta_2 & \delta_3 & \dots \end{array}$$

where  $\delta_{i+1} \leq \delta_i \cdot K$  for some fixed  $K < 1$ .

Then  $r_1, r_2, \dots$  is a Cauchy sequence.

Proof:  $\Delta_{n,m} \leq \delta_n + \delta_{n+1} + \dots + \delta_{n+m-1}$

$$\leq \delta_n (1 + K + K^2 + \dots + K^{m-1})$$

$$\leq \delta_n (1 + K + \dots) = \delta_n \frac{1}{1-K}$$

Given any  $\epsilon > 0$ , choose  $n$  such that  $\delta_n < \epsilon \cdot (1-K)$ .

# Contraction Mappings

def: A function  $f: X \rightarrow X$  on a metric space  $X$  is a contraction map if  $d(f(x), f(y)) \leq d(x, y) \cdot K$  for some fixed  $K < 1$ .

Thm. A contraction map on a non-empty, complete metric space has a unique fixed point.

Proof: Choose  $x \in X$ . Then by the previous lemma,

$$x, f(x), f^2(x), f^3(x), \dots$$

is a Cauchy sequence which therefore converges to a limit  $L$ . Since  $f$  is continuous, the net

$$f(x), f^2(x), f^3(x), \dots$$

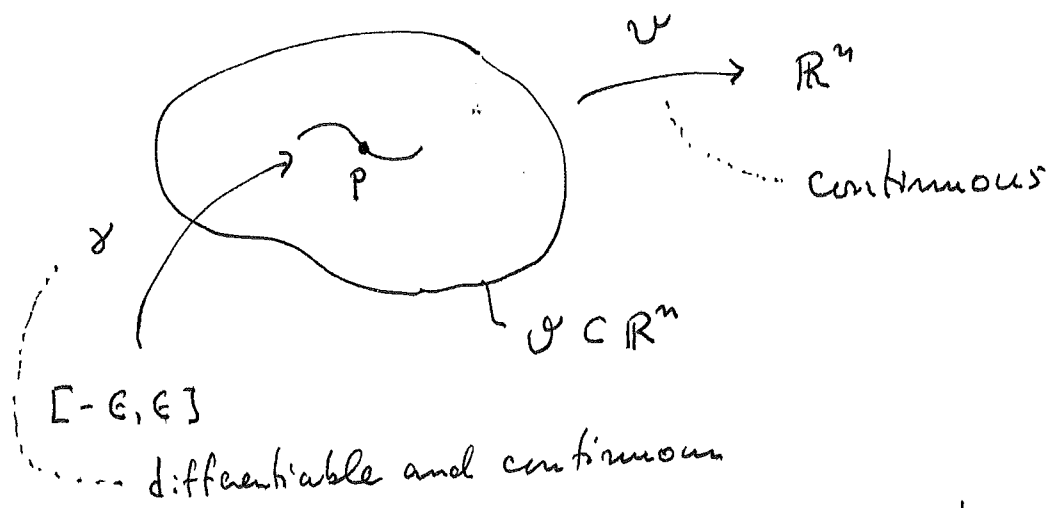
must converge to  $f(L)$ .  $\Rightarrow f(L) = L$  is a fixed point.

Suppose  $M$  is another fixed point. Then

$$d(L, M) = d(f(L), f(M)) \leq d(L, M) \cdot K$$

$$\Rightarrow d(L, M) = 0 \Rightarrow L = M.$$

# Picard's Theorem



Find  $\gamma: [-\epsilon, \epsilon] \rightarrow \mathcal{G}$  with  $\gamma(0) = p$  and

$$\frac{d\gamma}{dt}(t) = v(\gamma(t)) \quad \text{for } t \in (-\epsilon, \epsilon).$$

$$\Leftrightarrow \gamma(t) = p + \int_0^t v(\gamma(t)) dt$$

$$\Leftrightarrow \bar{\Psi}(\gamma) \equiv p + \int_0^t v(\gamma(t)) dt \quad \text{has a fixed point}$$

for  $\gamma \in X \equiv \{ \text{continuous differentiable functions} \\ \text{from } (-\epsilon, \epsilon) \text{ to } \mathcal{G} \}$

where  $d(\gamma, \gamma') \equiv \|\gamma - \gamma'\|$ ,  $\|\gamma\| \equiv \max_{t \in (-\epsilon, \epsilon)} \|\gamma(t)\|$

is a norm.

We'll try to find conditions such that  $\bar{\Psi}$  is a contraction mapping on  $X$  which would guarantee a unique solution.

$$d(\Psi(x), \Psi(x')) = \max_{t \in [-\epsilon, \epsilon]} \left\| \int_0^t v(x(t)) - v(x'(t)) dt \right\|$$

Suppose that  $v$  obeys a "Lipshitz" condition

$$\|v(p) - v(q)\| \leq \|p - q\| \cdot M$$

for some fixed  $M > 0$ , for all  $p, q \in \mathcal{O}$ . If this is so, then

$$\begin{aligned} d(\Psi(x), \Psi(x')) &\leq \epsilon \cdot \max \|x(t) - x'(t)\| \cdot M \\ &\leq \epsilon \cdot M \cdot d(x, x'). \end{aligned}$$

$\Rightarrow$  If we choose  $\epsilon < 1/M$ ,  $\Psi$  is a contraction and  $\dot{x}(t) = v(x(t))$  on  $[-\epsilon, \epsilon]$  for a unique function  $x: [-\epsilon, \epsilon] \rightarrow \mathcal{O}$ .

# This is a **CROSSROADS**

of many subjects

Tangent Space

Vector fields

Integral  
Curves

$$\frac{d\gamma}{dt} = v(\gamma(t))$$

ODE theory

Flow

One-parameter  
Subgroups of  
a Lie Group

Morse  
Theory

Dynamical Systems

The exponential  
function

Subtle behavior is possible even in one dimension, e.g.  $v(x) = x^{2/3}$  has two integral curves at  $x = 0$ .