

$$\textcircled{1} E_n = \frac{\hbar^2 \pi^2 n^2}{2ma^2} \rightarrow \boxed{E_2 - E_1 = \frac{3}{2} \frac{\hbar^2 \pi^2}{ma^2} = 1,14 \text{ eV}} \rightarrow \boxed{\lambda = \frac{hc}{\Delta E} = 1,14 \times 10^{-6} \text{ m}}$$

$\textcircled{2}$ The wave function does not remain localized at $t > 0$, since the phase relationship that allows for a total interference no longer persists for $t \neq 0$

~~Since~~ since a shift has no physical consequences the solution is the same as having the box extending from $x=0$ to $x=a$

$$C_n = \int_0^a \psi(x) u_n(x) dx = \frac{2}{a} \int_0^{a/2} \sin\left(\frac{n\pi}{a} x\right) dx = \frac{2}{n\pi} \left[1 - \cos\frac{n\pi}{2} \right]$$

$$u_n(x) = \sqrt{\frac{2}{a}} \sin\left(\frac{n\pi x}{a}\right)$$

$$P_1 = |C_1|^2 = |C_2|^2 = P_2 = \frac{4}{\pi^2}$$

$\textcircled{3}$ initially $\psi(x) = \sqrt{\frac{2}{a}} \cos\left(\frac{\pi}{2a} x\right)$ (see ground state prob. 2)
 $-\frac{a}{2} < x < \frac{a}{2}$

i) $P_1 = |C_1|^2$ with $C_1 = \int \psi(x) u_1(x) dx$ $u_1 = \sqrt{\frac{1}{b}} \cos\left(\frac{\pi}{2b} x\right)$

$$\boxed{C_1 = \sqrt{\frac{2}{ab}} \int_{-a/2}^{a/2} dx \cos\left(\frac{\pi x}{a}\right) \cos\left(\frac{\pi x}{2b}\right) = \frac{\sqrt{2ab^3}}{\pi(4b^2 - a^2)} \cos\left(\frac{\pi a}{4b}\right)}$$

ii) $P_2 = |C_2|^2$ $C_2 = \int_{-a/2}^{a/2} \underbrace{\psi(x)}_{\text{even}} \underbrace{u_2(x)}_{\text{odd}} dx = 0 \rightarrow \boxed{P_2 = 0}$

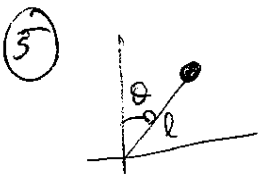
$$\textcircled{4} \quad \phi(p) = \frac{1}{\sqrt{2\pi}} \int_{-\infty}^{\infty} \psi(x) e^{-ipx/\hbar} = \left(\frac{1}{\pi\alpha\hbar^2}\right)^{1/4} e^{-p^2/2\alpha\hbar^2}$$

Probability of p being between p and $p+dp$ is $|\phi(p)|^2 dp$

$$E = \frac{p^2}{2m} \rightarrow \langle E \rangle = \frac{1}{2m} \langle p^2 \rangle = \frac{1}{2m} \left(\frac{1}{\pi\alpha\hbar^2}\right)^{1/2} \int_{-\infty}^{\infty} dp p^2 e^{-p^2/\alpha\hbar^2} = \frac{\alpha\hbar^2}{2m}$$

$$\Delta x \approx \frac{1}{\sqrt{\alpha}} \quad \text{from uncertainty principle} \quad \Delta p \approx \hbar/\Delta x = \hbar\sqrt{\alpha}$$

$$\approx E \approx \frac{(\Delta p)^2}{2m} = \frac{\alpha\hbar^2}{2m}$$



initial angle θ_0 , initial angular momentum L_0
 pencil = mass at end of a massless stick

$$\Delta x \cdot \Delta p \approx \hbar \rightarrow l\theta_0 \cdot l m \omega_0 \approx \hbar \rightarrow \theta_0 \omega_0 \approx \frac{\hbar}{m l^2}$$

$$m l \ddot{\theta} = m g \sin \theta \rightarrow \ddot{\theta} = \frac{g}{l} \sin \theta \approx \frac{g}{l} \theta \quad \left(\text{only valid for small } \theta \text{ (but good for an estimation)}\right)$$

$$\rightarrow \theta(t) = A e^{-t/\tau} + B e^{t/\tau} \quad \text{with } \tau = \sqrt{l/g}$$

initial cond. $A+B = \theta_0 \rightarrow B = \frac{\theta_0 + \omega_0 \tau}{2}$
 $A-B = \omega_0 \tau$

$$\theta(t^*) = \frac{\tau}{2} \approx B e^{t^*/\tau} \quad (\text{assuming } t^* \gg \tau) \rightarrow t^* \approx \tau \ln \left(\frac{\tau}{\theta_0 + \omega_0 \tau} \right)$$

$$t^* \approx \tau \ln \left(\frac{\tau \theta_0}{\theta_0^2 + \theta_0 \omega_0 \tau} \right) = \tau \ln \left(\frac{\tau \theta_0}{\theta_0^2 + \frac{\hbar}{m \sqrt{gl^3}}} \right) = \tau \ln \left[\frac{\tau}{\alpha} \frac{\theta_0/\alpha}{(\theta_0/\alpha)^2 + 1} \right] \quad \text{maximum for } \theta_0 \approx \alpha$$

$$t^* \approx \tau \ln \alpha^{-1}$$

$$\alpha^2 = \frac{\hbar}{m \sqrt{gl^3}} = \frac{10^{-34}}{10^{-3} (10 \cdot 10^{-6})^{3/2}} \approx 10^{-29} \rightarrow \alpha \approx 10^{-29/2} \rightarrow \boxed{t^* \approx \sqrt{\frac{l}{g}} \ln 10^{29/2} \approx 30 \sqrt{\frac{l}{g}}} \quad t^* \gg \tau \checkmark$$