

MORE C++ AND ROOT

TODAY'S LECTURE

- Series of topics from C++
- Example of thinking through a problem
- Useful physics classes in ROOT

FUNCTIONS

```
const double PI = 3.14159265;    // global constant
double ellipseArea(double, double); // prototype
int main() {
    double a = 5;
    double b = 7;
    double area = ellipseArea(a, b);
    cout << "area = " << area << endl;
    return 0;
}

double ellipseArea(double a, double b) {
    return PI*a*b;
}
```

- by this point you are used to the syntax of a function

PASS BY VALUE

```
void tryToChangeArg(int x) {  
    x = 2*x;  
}
```

- Imagine that you wrote the following code
- What would be the output ?

```
int x = 1;  
tryToChangeArg(x) ;  
cout << "now x = " << x << endl;
```


PASS BY VALUE

- Imagine that you wrote the following code
- What would be the output ?
- you might be tempted to say 2 but the answer is 1

```
void tryToChangeArg(int x) {  
    x = 2*x;  
}
```

```
int x = 1;  
tryToChangeArg(x) ;  
cout << "now x = " << x << endl;
```


PASS BY VALUE

```
void tryToChangeArg(int x) {  
    x = 2*x;  
}
```

- passing by value takes the value of the variable and assigns it to a new local copy of the variable
- Inside the function the local copy gets changed to 2

```
int x = 1;  
tryToChangeArg(x) ;  
cout << "now x = " << x << endl;
```


PASS BY VALUE

- passing by value takes the value of the variable and assigns it to a new local copy of the variable
- Inside the function the local copy gets changed to 2
- However, after the function ends nothing is returned and so outside the function the value of x is still 1

```
void tryToChangeArg(int x) {  
    x = 2*x;  
}
```

```
int x = 1;  
tryToChangeArg(x);  
cout << "now x = " << x << endl;
```


PASS BY REFERENCE

- There is another way to do this
- This takes the address of the variable and passes a reference to the variable outside the function
- IN this case it DOES return 2

```
void tryToChangeArg(int&) ;  
void tryToChangeArg(int& x) {  
    x = 2*x;  
}  
  
int main() {  
    int x = 1;  
    tryToChangeArg(x) ;  
    cout << "now x = " << x << endl;  
}
```


SCOPE

```
double pow(double x, int n){  
    double y = static_cast<double>(n) * log(x);  
    return exp(y);  
}  
  
...  
double y = pow(3,2); // this is a different y
```

- The variable `y` in the definition of `pow` is local.
- We can use the same variable name outside this function with no effect on or from the variable `y` inside `pow`.
- We say that the scope of `y` inside `pow` is inside

DEFAULT ARGUMENTS

```
double line(double x, double slope=1, double offset=0);
```

Define as usual

```
double line(double x, double slope, double offset){  
    return x*slope + offset;  
}
```

```
y = line (x, 3.7, 5.2); // here slope=3.7, offset=5.2  
y = line (x, 3.7);      // uses offset=0;  
y = line (x);           // uses slope=1, offset=0
```


FUNCTION OVERLOAD

- Can have multiple functions
- which one gets called depends on type of argument passed

```
double cube(double);  
double cube (double x) {  
    return x*x*x;  
}  
  
double cube(float);  
double cube (float x) {  
    double xd = static_cast<double>(x);  
    return xd*xd*xd;  
}
```


FUNCTION OVERLOAD

```
float x;  
double y;  
double z = cube(x); // calls cube(float) version  
double z = cube(y); // calls cube(double) version
```

- Can have multiple functions
- called “overloading”

ARRAYS

- The number in brackets [] gives the total number of elements,e.g. the array score above has 10 elements, numbered 0 through 9.
- The individual elements are referred to as score[0], score[1], score[2], ..., score[9]
- Declaring an array: data-type variableName[numElements];
- `int score[10];`
- If you try to access score[10] this is an error!

```
int score[10];  
double energy[50], momentum[50];  
const int MaxParticles = 100;  
double ionizationRate[MaxParticles];
```


ARRAYS

- An array can also have two or more indices. A two-dimensional array is often used to store the values of a matrix:
- `const int numRows = 2;`
- `const int numColumns = 3;`
- `double matrix[numRows][numColumns];`
- Again, notice that the array size is 2 by 3, but the row index runs from 0 to 1 and the column index from 0 to 2.
- `matrix[i][j]`, `matrix[i][j+1]`, etc.
- The elements are stored in memory in the order:
- Usually we don't need to know how the data are stored internally

INITIALIZATION

One dimensional array:

```
int myArray[5] = {2, 4, 6, 8, 10};
```

Multidimension:

```
double matrix[numRows][numColumns] =  
    { {3, 7, 2}, {2, 5, 4} };
```


EXAMPLE

```
// Initialize vector x and matrix A
const int n = 5;
double x[n];
double A[n][n];
for (int i=0; i<n; i++){
    x[i] = someFunction(i);
    for (int j=0; j<n; j++){
        A[i][j] = anotherFunction(i, j);
    }
}

// Now find y = Ax
double y[n];
for (int i=0; i<n; i++){
    y[i] = 0.0;
    for (int j=0; j<n; j++){
        y[i] += A[i][j] * x[j];
    }
}
```


PASSING TO A FUNCTION

- when we pass an array to a function in the actual call we don't need the brackets
- If we include a specific element of the array then we are actually evaluating that first - in this case a double which happens to be the *i*th element of the `myMatrix`

```
double sumElements(double a[], int len){  
    double sum = 0.0;  
    for (int i=0; i<len; i++){  
        sum += a[i];  
    }  
    return sum;  
}
```

```
double s = sumElements(myMatrix, itsLength);
```

```
double x = sqrt(myMatrix[i]);
```


PASS BY REFERENCE

```
void changeArray (double a[], int len){  
    for(int i=0; i<len; i++){  
        a[i] *= 2.0;  
    }  
}  
  
int main() {  
    ...  
    changeArray(a, len);    // elements of a doubled
```

- note - passing an array to a function works like pass by reference!

POINTERS

- A pointer is the address of a variable in memory
- The notation is to use the * when declaring a pointer
- Note that as long as the star is between the type and the name it doesn't matter!

```
int* iPtr;  
double * xPtr;  
char *c;  
float *x, *y;
```


POINTERS

- Here & means “address of”. Don’t confuse it with the & used when passing arguments by reference.

```
int i = 3;
```

```
int* iPtr = &i;
```


INITIALIZING POINTERS

- A statement like
- `int* iPtr;`
- declares a pointer variable, but does not initialize it. It will be
- pointing to some “random” location in memory. We need
- to set its value so that it points to a location we’re interested in,
- e.g., where we have stored a variable:
- `iPtr = &i;`
- (just as ordinary variables must be initialized before use).

DIFFERENT POINTERS

```
int* iPtr;      // type "pointer to int"  
float* fPtr;    // type "pointer to float"  
double* dPtr;   // type "pointer to double"
```

- We need different types of pointers because in general, the different data types (int, float, double) take up different amounts of memory.
- If declare another pointer and set then the +1 means “plus one unit of memory address for int”, i.e., if we had int variables stored contiguously, jPtr would point to the one just after iPtr.
- But the types float, double, etc., take up different amounts of memory, so the actual memory address increment is different.

```
int* jPtr = iPtr + 1;
```


POINTERS IN FUNCTIONS

```
void passPointer(int* iPtr){  
    *iPtr += 2;           // note *iPtr on left!  
}  
  
...  
int i = 3;  
int* iPtr = &i;  
passPointer(iPtr);  
cout << "i = " << i << endl;    // prints i = 5  
passPointer(&i);                // equivalent to above  
cout << "i = " << i << endl;    // prints i = 7
```

When a pointer is passed as an argument, it divulges an address to the called function, so the function can change the value stored at that address - acts like pass by reference...

TEST

What would this piece of code output?

```
int i = 3;  
int& j = i;           // j is a  
j = 7;  
cout << "i = " << i << endl;
```


TEST

What would this piece of code output?

```
int i = 3;  
int& j = i;           // j is a  
j = 7;  
cout << "i = " << i << endl;
```

i is now 7! The second line assigns the address of the variable j to i. Change j and now you also change i

WHAT TO DO WITH POINTERS

- You can do lots of things with pointers in C++, many of which result in confusing code and hard-to-find bugs.
- One of the main differences between Java and C++: Java doesn't have pointer variables (generally seen as a Good Thing).
- The main usefulness of pointers for us is that they will allow us to allocate memory (create variables) dynamically, i.e., at run time, rather than at compile time.
- Be careful - the misallocation of memory in C++ is a major source of memory leaks, bugs, and general obfuscation . General advice: keep it as simple as possible

CLASSES IN C++

- A class is something like a user-defined data type.
- Typically this would be in a file called `MyClassName.h` and the definitions of the functions would be in `MyClassName.C`
- Note the semi-colon after the closing brace.

```
class MyClassName {  
    public:  
        public function prototypes and  
        data declarations;  
        ...  
    private:  
        private function prototypes and  
        data declarations;  
        ...  
};
```


EXAMPLE CLASS

Say we wanted to represent
vectors in 2-D we might
make a class like:

```
class TwoVector {  
    public:  
        TwoVector();  
        TwoVector(double x, double y);  
        double x();  
        double y();  
        double r();  
        double theta();  
        void setX(double x);  
        void setY(double y);  
        void setR(double r);  
        void setTheta(double theta);  
    private:  
        double m_x;  
        double m_y;  
};
```


CLASS HEADER

- The header file must be included (`#include "MyClassName.h"`) in other files where the class will be used.
- To avoid multiple declarations we use a

```
#ifndef TWOVECTOR_H
#define TWOVECTOR_H

class TwoVector {
    public:
        ...
    private:
        ...
};

#endif
```


OBJECTS

```
double a;    // a is a variable of type double
```

```
#include "TwoVector.h"
int main() {
    TwoVector v;  // v is an object of type TwoVector
```

- (Actually, variables are also objects in C++. Sometimes class instances are called “class objects” -- distinction is not important.)
- A class contains in general both:
 - variables, called “data members” and
 - functions, called “member functions” (or “methods

DATA MEMBERS

```
private:  
    double m_x;  
    double m_y;
```

- Their values define the “state” of the object. Because here they are declared private, a TwoVector object’s values of m_x and m_y cannot be accessed directly, but only from within the class’s member functions (more later).
- The optional prefixes m_ indicate that these are data members.
- Some authors use e.g. a trailing underscore. (Any valid identifier is allowed.)

CONSTRUCTORS

- These are special functions called constructors.
- A constructor always has the same name as that of the class.
- It is a function that is called when an object is created.
- A constructor has no return type.
- There can be in general different constructors with different signatures (type and number of arguments).

```
public:  
    TwoVector() ;  
    TwoVector(double x, double y) ;
```


CONSTRUCTORS

When we declare an object, the constructor is called which has the matching signature, e.g.,

```
TwoVector u;    // calls TwoVector::TwoVector()
```

The constructor with no arguments is called the “default constructor”. If, however, we say

```
TwoVector v(1.5, 3.7);
```

then the version that takes two double arguments is called. If we provide no constructors for our class, C++ automatically gives us a default constructor

IN ACTION

In the file that defines the member functions, e.g., `TwoVector.cc`, we precede each function name with the class name and `::` (the scope resolution operator). For our two constructors we have:

```
TwoVector::TwoVector() {  
    m_x = 0;  
    m_y = 0;  
}  
  
TwoVector::TwoVector(double x, double y) {  
    m_x = x;  
    m_y = y;  
}
```

The constructor serves to initialize the object.

If we already have a `TwoVector v` and we say

`TwoVector w = v;`

this calls a “copy constructor” (automatically provided).

FUNCTIONS

```
void TwoVector::setX(double x) { m_x = x; }  
void TwoVector::setY(double y) { m_y = y; }  
void TwoVector::setR(double r) {  
    double cosTheta = m_x / this->r();  
    double sinTheta = m_y / this->r();  
    m_x = r * cosTheta;  
    m_y = r * sinTheta;  
}
```

These are “setter” functions. As they belong to the class, they are allowed to manipulate the private data members `m_x` and `m_y`. To use with an object, use the “dot” notation:

```
TwoVector v(1.5, 3.7);  
v.setX(2.9);           // sets v's value of m_x to 2.9
```


POINTERS TO OBJECTS

```
TwoVector* vPtr; // type "pointer to TwoVector"
```

This doesn't create an object yet! This is done with, e.g.,

```
vPtr = new TwoVector(1.5, 3.7);
```

vPtr is now a pointer to our object. With an object pointer, we call member functions (and access data members) with **->** (not with **."**), e.g.,

```
double vX = vPtr->x();
```

```
cout << "vX = " << vX << endl; // prints vX = 1.5
```


THIS POINTER

```
void TwoVector::setR(double r) {  
    double cosTheta = m_x / this->r();  
    double sinTheta = m_y / this->r();  
    m_x = r * cosTheta;  
    m_y = r * sinTheta;  
}
```

- C++ defines a pointer “this” which is a pointer to the object that is being called

INFORMATION HIDING

- Note that by declaring the `m_x` and `m_y` private this means that we can only access them via the 'accessor' functions
- Why do we do this?

C++ PARADIGM

- The basic idea of the C++ paradigm is to 'hide' the implementation of private member data or function
- This way - if the implementation changes inside the class. None of the user code needs to know about it!
- This way we can encapsulate the behavior in a small piece of code that is used by a large number of clients

EXAMPLE

- Let's write a program that checks to see if a number between 1 and 1000 is a prime number

LET'S THINK

- How do we decide if a number is prime.

LET'S THINK

- How do we decide if a number is prime.
- If it is only divisible by itself and 1 then it is prime

So

- So a straightforward way to test this is to just try to divide the number by every number between 2 and N (where N is the test number) and see if there is any factors



- first we will get an input from the keyboard to see what number we have to test
- `get_valid_number()`

```
int main()
{
    int number;

    cout << "This program tests to see if an integer\n";
    cout << "is a prime between 1 and 1000.\n\n\n";

    number = get_valid_number();
    while (number != 0) {
        cout << "The number " << number << " is ";
        if (!small_prime(number))
            cout << "not ";
        cout << "a prime between 1 and 1000.\n\n";
        number = get_valid_number();
    }

    return 0;
}
```


RETRIEVE THE NUMBER

- Get a number, if it is out of range output a error message and stay in the loop
- if it is inside exit loop and return the number

```
int get_valid_number()
{
    int number;
    do {
        cout << "Enter an integer between 1 and 1000 (incl) (or 0 to end program): ";
        cin >> number;
        if (number < 0 || number > 1000)
            cout << "number out of range, try again!" << endl;
    } while (number < 0 || number > 1000);

    return number;
}
```


NEXT STEP

- After a valid input check to see if it is prime

```
int main()
{
    int number;

    cout << "This program tests to see if an integer\n";
    cout << "is a prime between 1 and 1000.\n\n\n";

    number = get_valid_number();
    while (number != 0) {
        cout << "The number " << number << " is ";
        if (!small_prime(number))
            cout << "not ";
        cout << "a prime between 1 and 1000.\n\n";
        number = get_valid_number();
    }

    return 0;
}
```


PRIME CHECKER

- Iterate through all numbers from 2 to N-1 and check to see if there is a remainder or not
- If you can't find one return true

```
Logical small_prime(int integer)
{
    for (int factor = 2; factor < integer; factor++) {
        if ((integer % factor) == 0)
            return False;
    }
    return True;
}
```


ROOT PHYSICS CLASSES

- Example code on blackboard
- An example introducing some convenient physics classes

```
if (!gROOT->GetClass("TGenPhaseSpace")) gSystem.Load("libPhysics");

TLorentzVector target(0.0, 0.0, 0.0, 0.938);
TLorentzVector beam(0.0, 0.0, .65, .65);
TLorentzVector W = beam + target;

//(Momentum, Energy units are GeV/c, GeV)
Double_t masses[3] = { 0.938, 0.139, 0.139} ;

TGenPhaseSpace event;
event.SetDecay(W, 3, masses);

TH2F *h2 = new TH2F("h2","h2", 50,1.1,1.8, 50,1.1,1.8);

for (Int_t n=0;n<100000;n++) {
    Double_t weight = event.Generate();

    TLorentzVector *pProton = event.GetDecay(0);

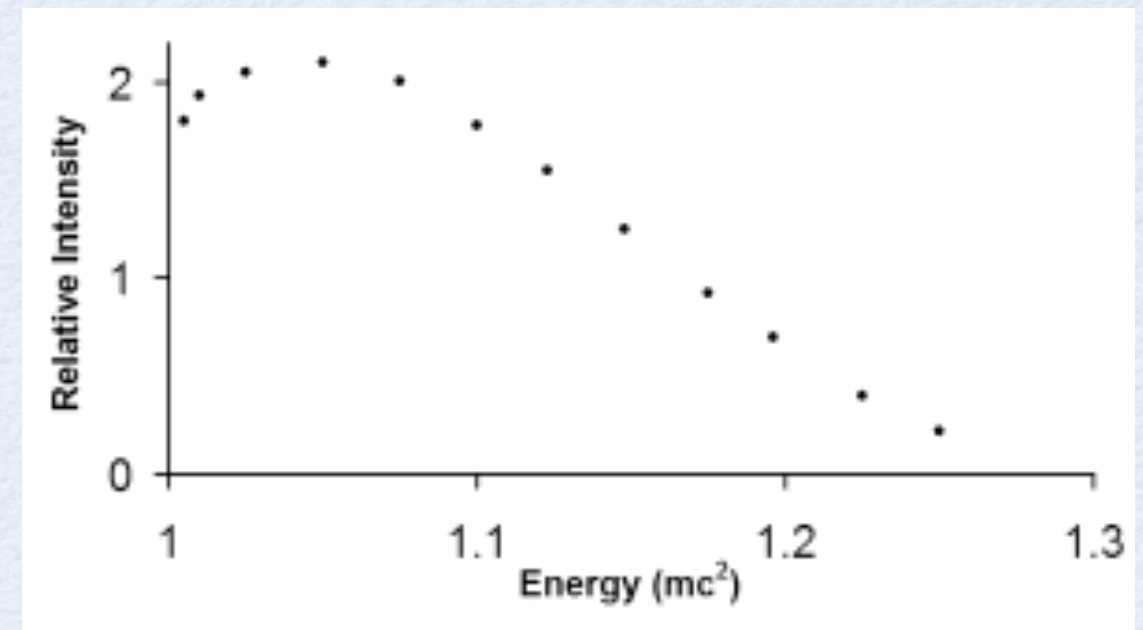
    TLorentzVector *pPip    = event.GetDecay(1);
    TLorentzVector *pPim    = event.GetDecay(2);

    TLorentzVector pPPip = *pProton + *pPip;
    TLorentzVector pPPim = *pProton + *pPim;

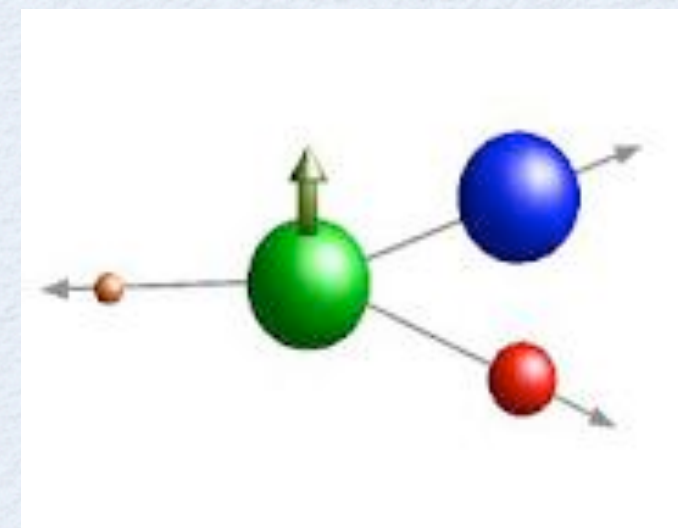
    h2->Fill(pPPip.M2() ,pPPim.M2() ,weight);
}
h2->Draw();
```


ASIDE : 2 VERSUS 3 BODY DECAY

- For a 2 body decay as you showed in your homework you must have a fixed energy in the rest frame of the decaying particle. Conservation of energy and momentum
- For a 3 body decay there is enough phase space that you expect a continuous rather than discrete spectrum of energy



β decay spectrum



TLorentzVector

- <http://root.cern.ch/root/html/TLorentzVector.html>
- Constructors, and many member functions which both access the internal data and know how to rotate, boost, and add Lorentzvectors

public:

```
    TLorentzVector (const Double_t* carray)
    TLorentzVector (const Float_t* carray)
    TLorentzVector (const TLorentzVector& lorentzvector)
    TLorentzVector (const TVector3& vector3, Double_t t)
    TLorentzVector (Double_t x = 0.0, Double_t y = 0.0, Double_t z = 0.0, Double_t t = 0.0)
    virtual ~TLorentzVector ()
    Double_t Angle (const TVector3& v) const
    Double_t Beta () const
    void Boost (const TVector3& b)
    void Boost (Double_t, Double_t, Double_t)
    TVector3 BoostVector () const
    static TClass* Class ()
    Double_t CosTheta () const
    Double_t DeltaPhi (const TLorentzVector& v) const
    Double_t DeltaR (const TLorentzVector& v) const
    Double_t Dot (const TLorentzVector& q) const
    Double_t DrEtaPhi (const TLorentzVector& v) const
    Double_t E () const
    Double_t Energy () const
    Double_t Et () const
    Double_t Et (const TVector3& v) const
    Double_t Et2 () const
    Double_t Et2 (const TVector3& v) const
    Double_t Eta () const
    TVector2 EtaPhiVector ()
    Double_t Gamma () const
    void GetXYZT (Double_t* carray) const
    void GetXYZT (Float_t* carray) const
    virtual TClass* IsA () const
    Double_t M () const
```


- Load library
- Construct two Lorentz Vectors

```
if (!gROOT->GetClass("TGenPhaseSpace")) gSystem.Load("libPhysics");

TLorentzVector target(0.0, 0.0, 0.0, 0.938);
TLorentzVector beam(0.0, 0.0, .65, .65);
TLorentzVector W = beam + target;

//(Momentum, Energy units are GeV/c, GeV)
Double_t masses[3] = { 0.938, 0.139, 0.139} ;

TGenPhaseSpace event;
event.SetDecay(W, 3, masses);

TH2F *h2 = new TH2F("h2","h2", 50,1.1,1.8, 50,1.1,1.8);

for (Int_t n=0;n<100000;n++) {
    Double_t weight = event.Generate();

    TLorentzVector *pProton = event.GetDecay(0);

    TLorentzVector *pPip    = event.GetDecay(1);
    TLorentzVector *pPim    = event.GetDecay(2);

    TLorentzVector pPPip = *pProton + *pPip;
    TLorentzVector pPPim = *pProton + *pPim;

    h2->Fill(pPPip.M2() ,pPPim.M2() ,weight);
}
h2->Draw();
```


- Load library
- Construct two LorentzVectors
- TGenPhaseSpace

```

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    h2->Fill(pPPip.M2() ,pPPim.M2() ,weight);
}
h2->Draw();

```


- <http://root.cern.ch/root/html/TGenPhaseSpace.html>
- Generates n-body phase space events (by default assumes constant cross-section) ie. only phase space comes in

- Set properties of phase space generator
- Create histogram
- Generate events
- Calculate the invariant mass of the proton and pion both positive and negative from the decay products
- Draw the histogram

```

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    TLorentzVector *pProton = event.GetDecay(0);

    TLorentzVector *pPip    = event.GetDecay(1);
    TLorentzVector *pPim    = event.GetDecay(2);

    TLorentzVector pPPip = *pProton + *pPip;
    TLorentzVector pPPim = *pProton + *pPim;

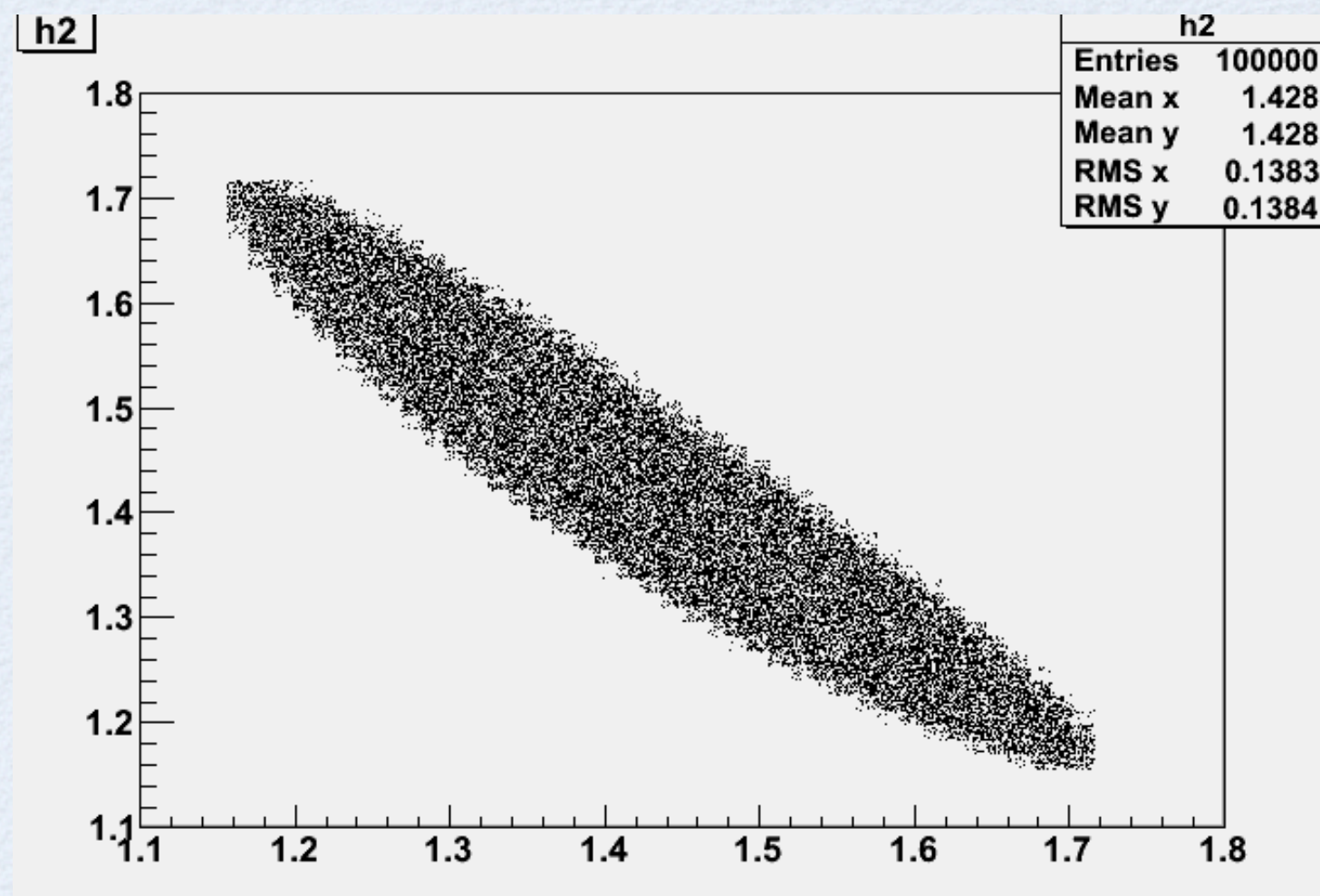
    h2->Fill(pPPip.M2() ,pPPim.M2() ,weight);
}
h2->Draw();

```


DALITZ PLOT

- What we have just generated is called a Dalitz plot
- Provides information on the phase space of three body decays
- Uniform if no angular correlations between decay products
- If resonant structures or correlations phase space is populated unequally

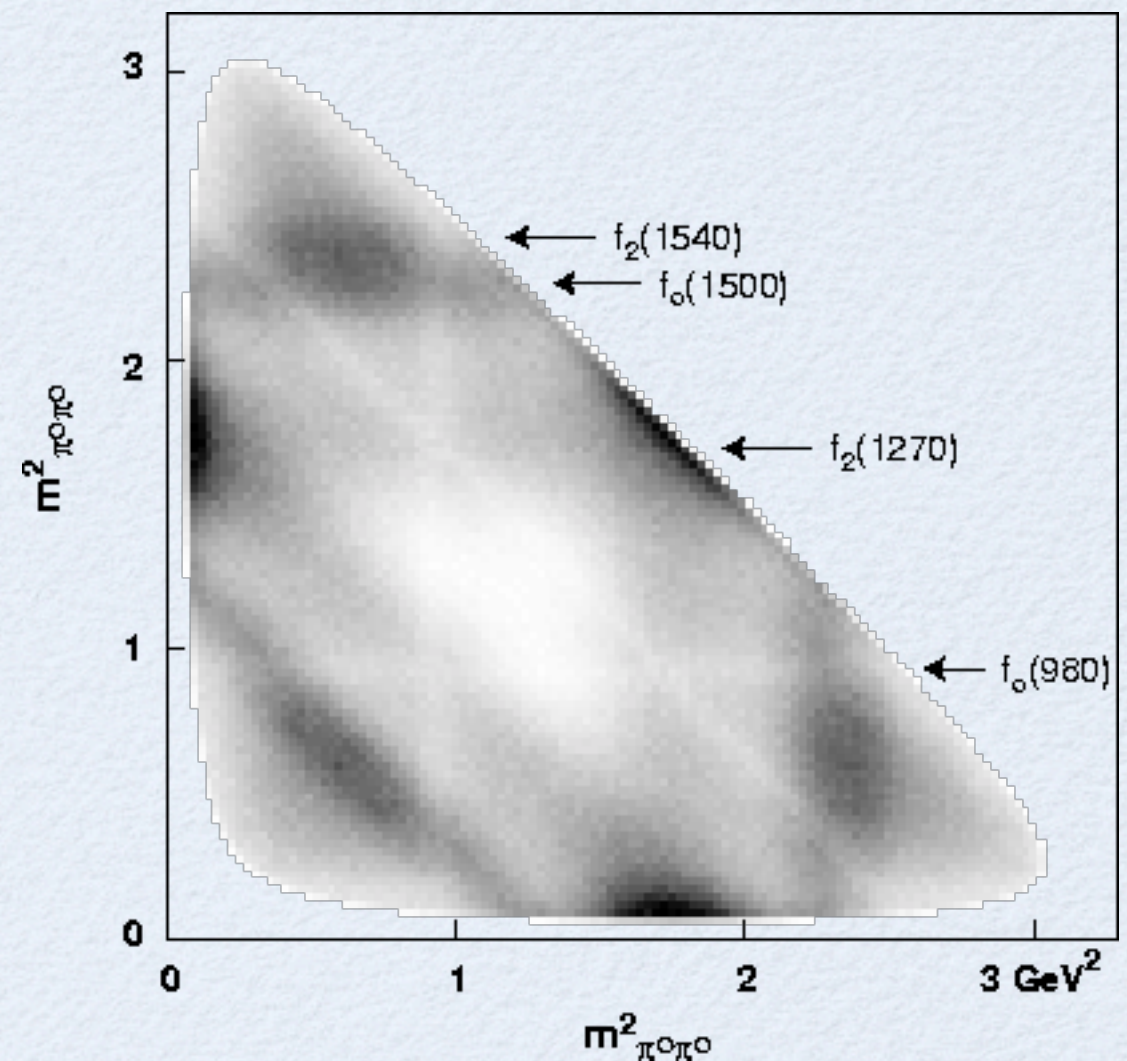
$M(\pi^+\bar{p})$



$M(\pi^-\bar{p})$

EXAMPLE

- proton+antiproton to three neutral pions
- clear structure and resonances reveals intermediate particles that were not seen by the detector itself but can be inferred from the measurements made!



NEXT WEEK

- Introduction to Limits (or how I learned to report just how much i didn't see new physics)
- Root statistics classes
- Presentations!!