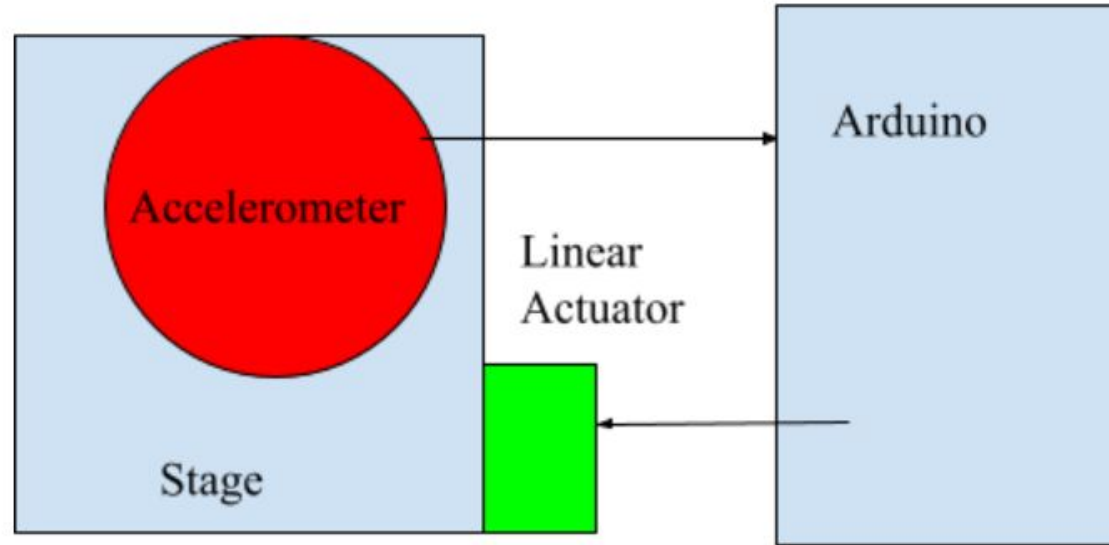


Active Vibration Damper

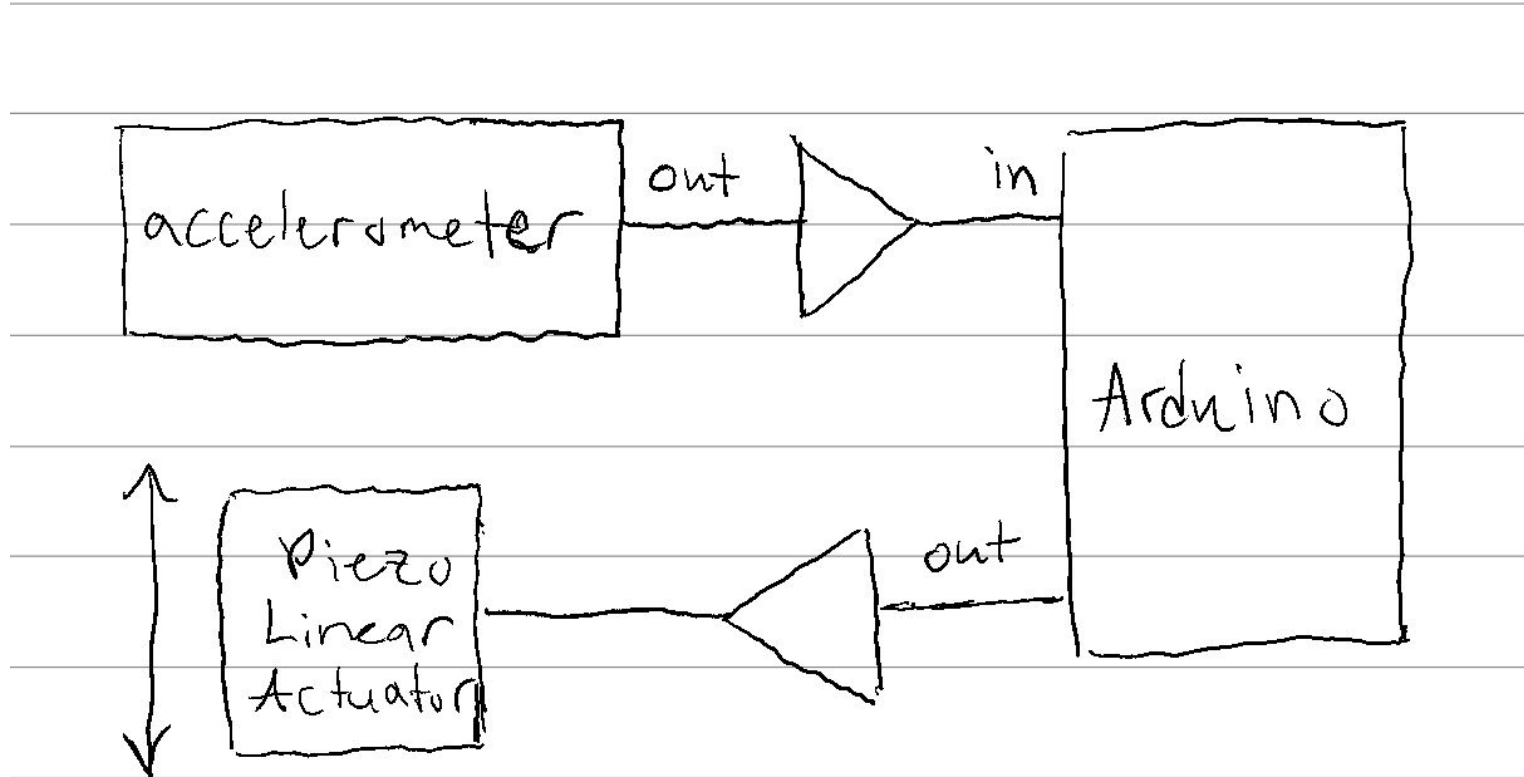
Mark Polkovnikov, Chris Hennighausen

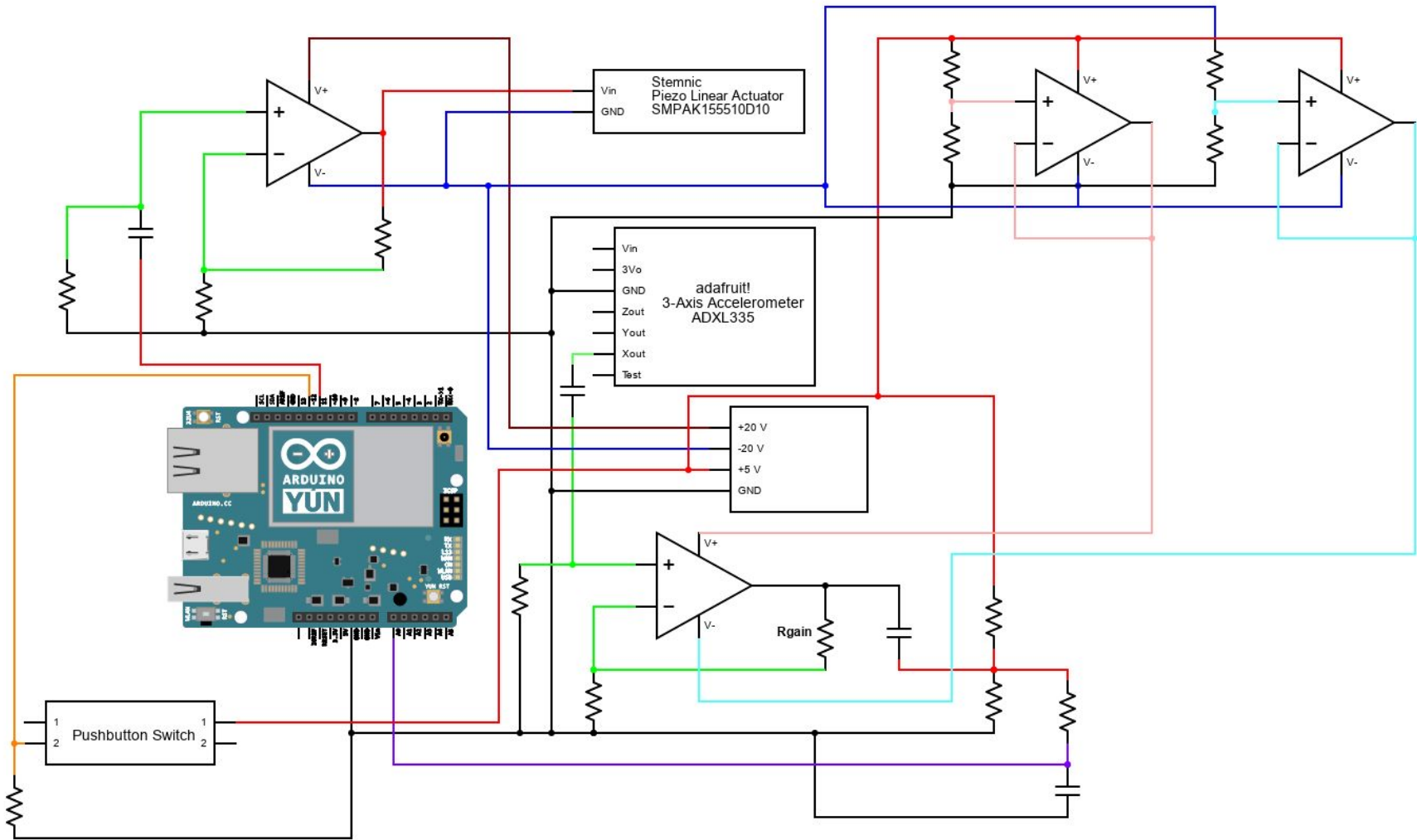
Abstract and Block Diagram

- Based on output of accelerometer, a brain (Arduino) outputs a signal to a linear actuator (Piezo) which damps the vibrations along one dimension



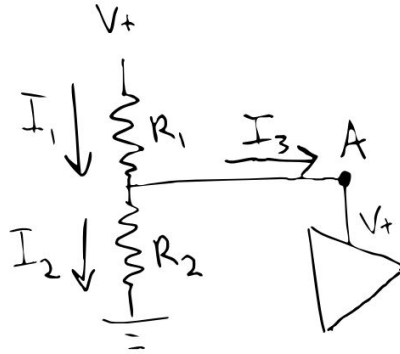
Block Diagram II



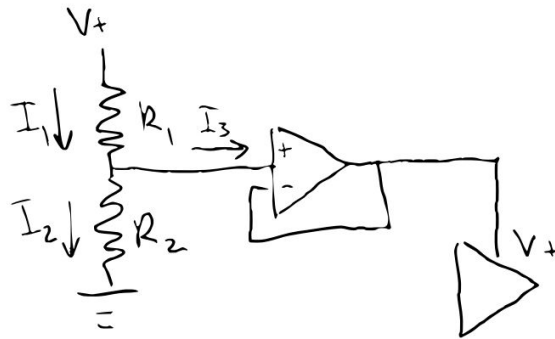


Stiff Voltage Divider

- Don't want Op-Amp to draw current directly from voltage divider
- Provide alternate current source (power source of Follower)



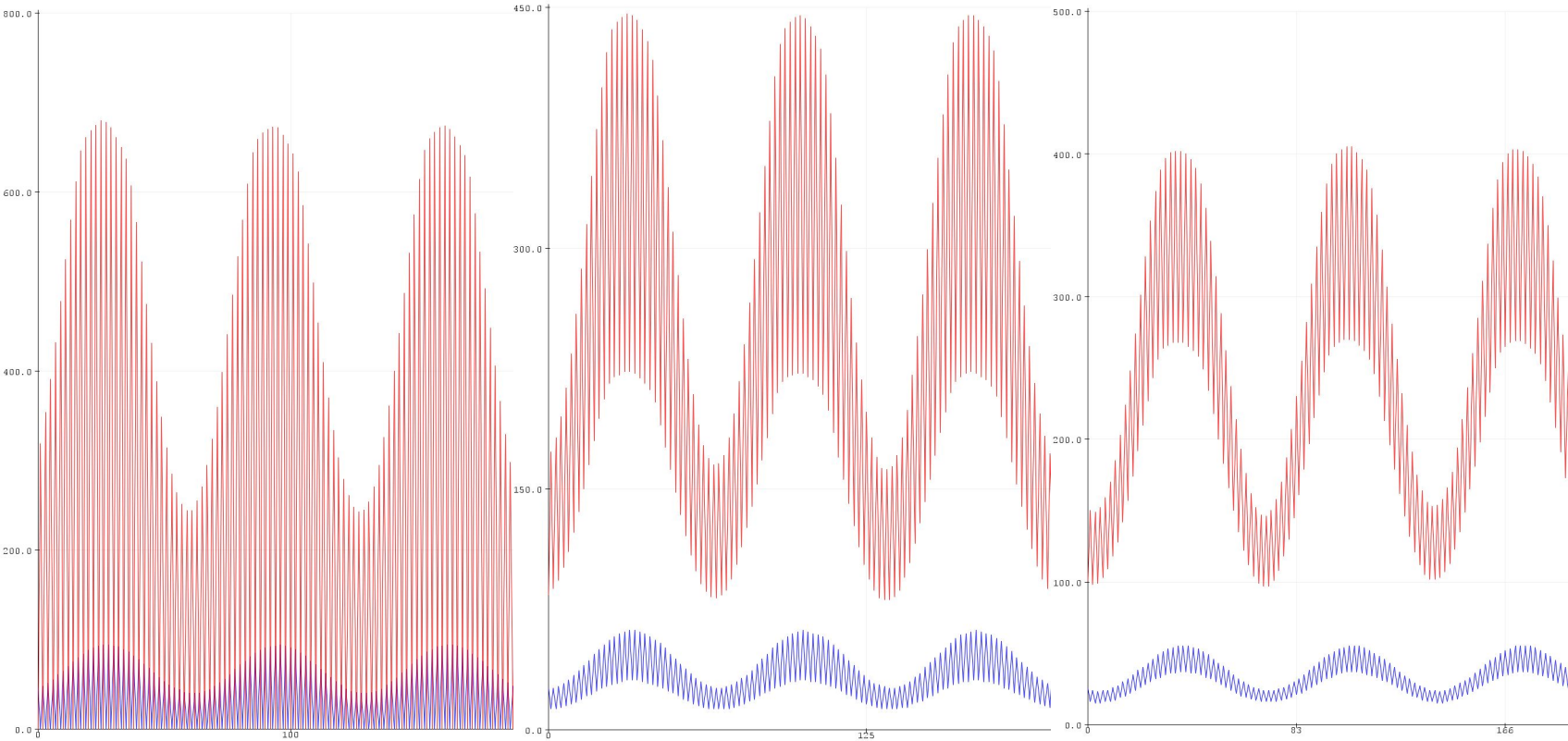
- Op-Amp draws large current
- $I_3 > I_2$
- V_A goes down ($< \frac{R_2}{R_1} V_+$)



- Follower provides high input impedance
- $I_3 \ll I_2 \Rightarrow I_1 \approx I_2$

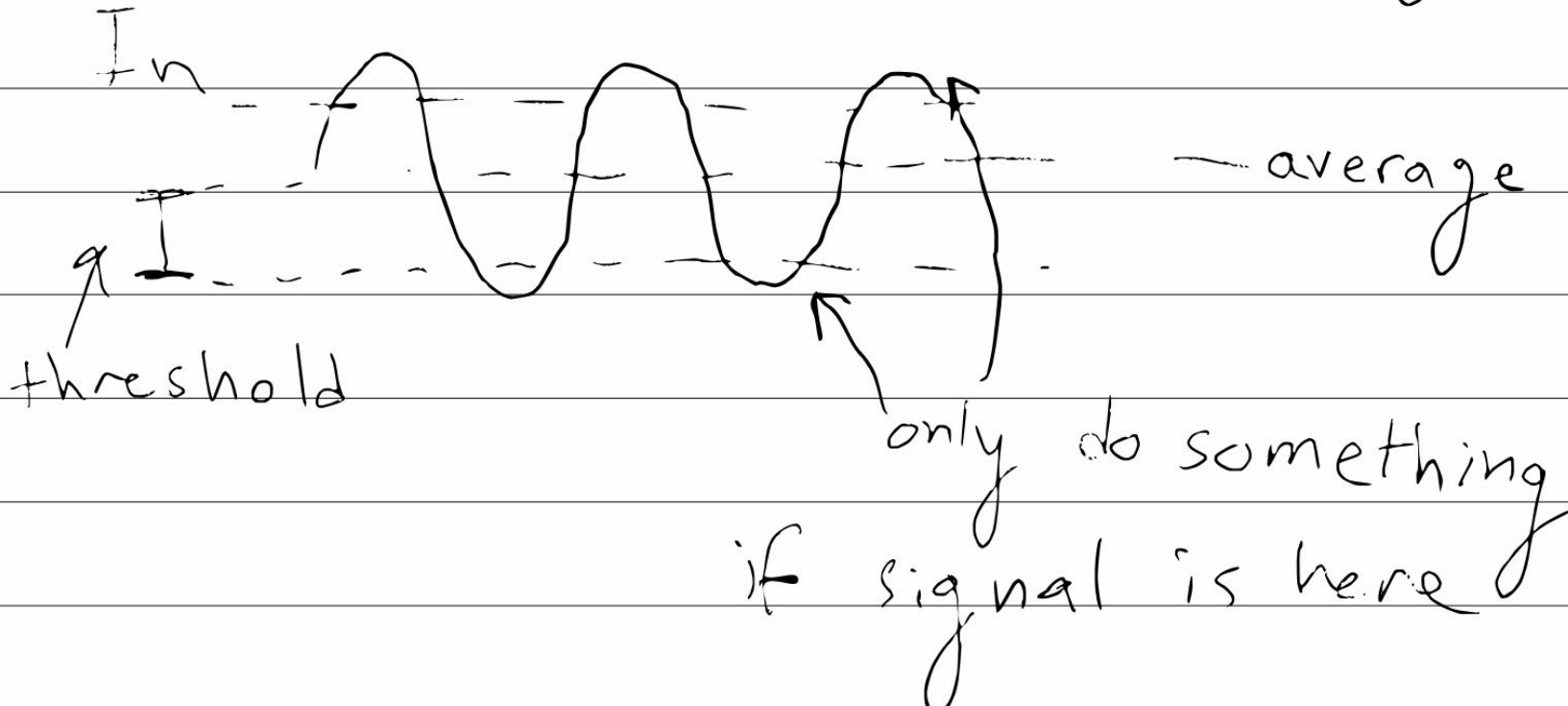
Detecting Speaker Signal on Arduino

- 100Hz speaker signal, arduino "scope", much noisier signal than on actual scope

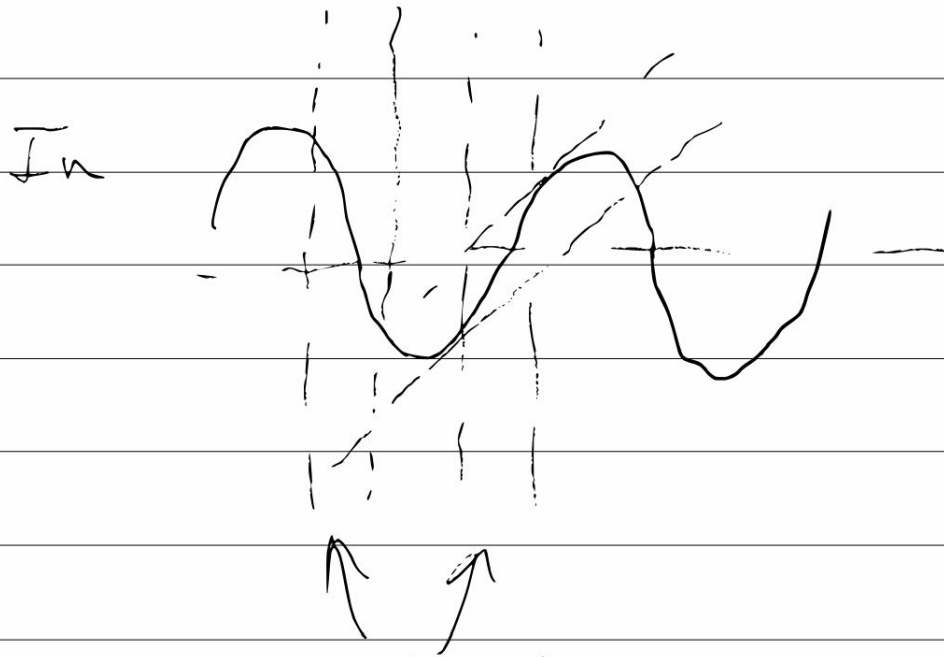


- Blue = input, red = output, from left to right - 1, 3, and 5 point averaging to reduce noise

Value Threshold Damping



Derivative Threshold Damping



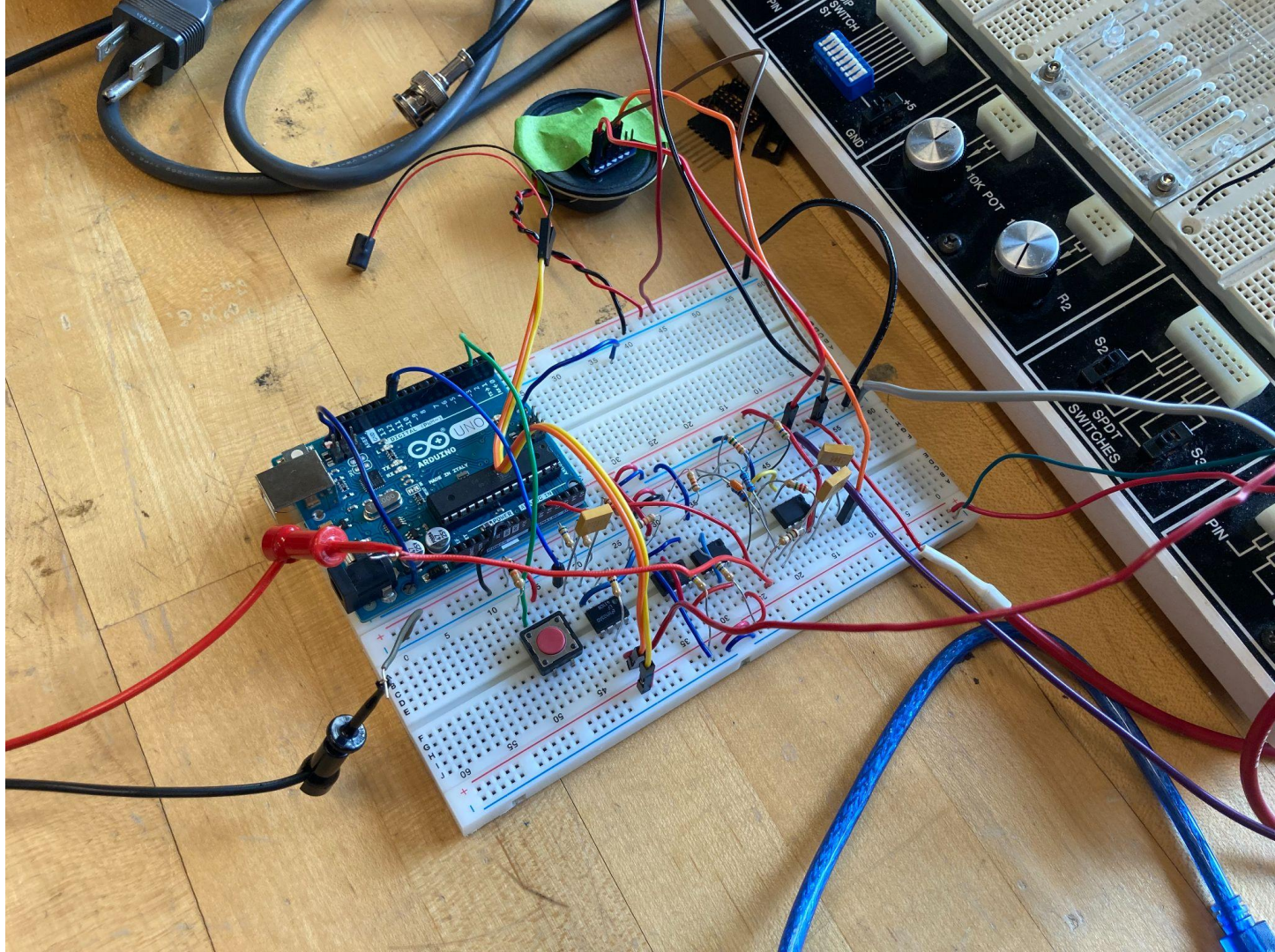
only do something if signal
is here

Arduino In vs Out on Scope



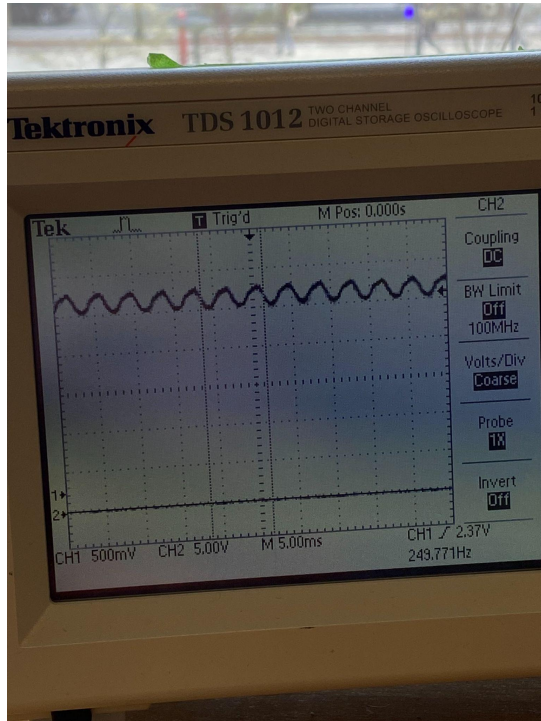
Setup

- Will move to microscope table

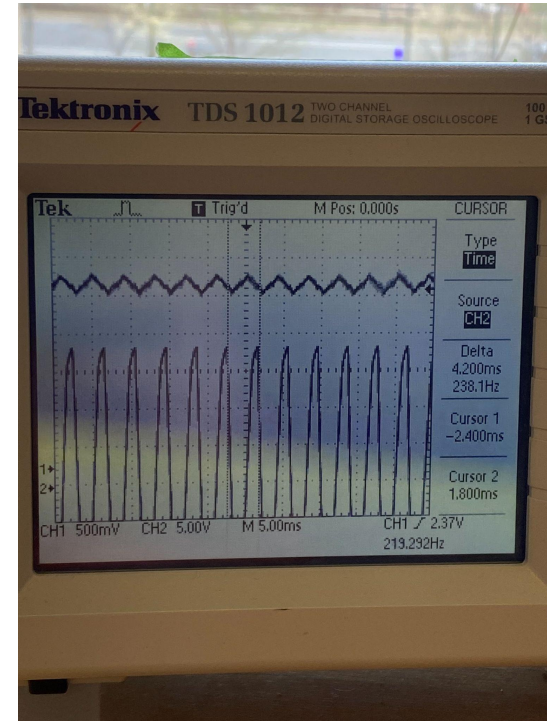


Accelerometer Reading

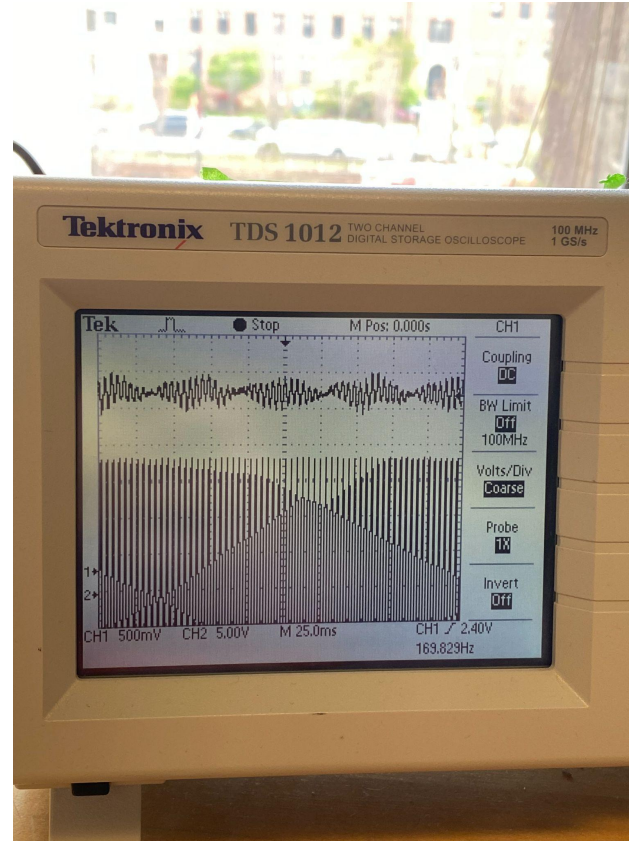
From Speaker



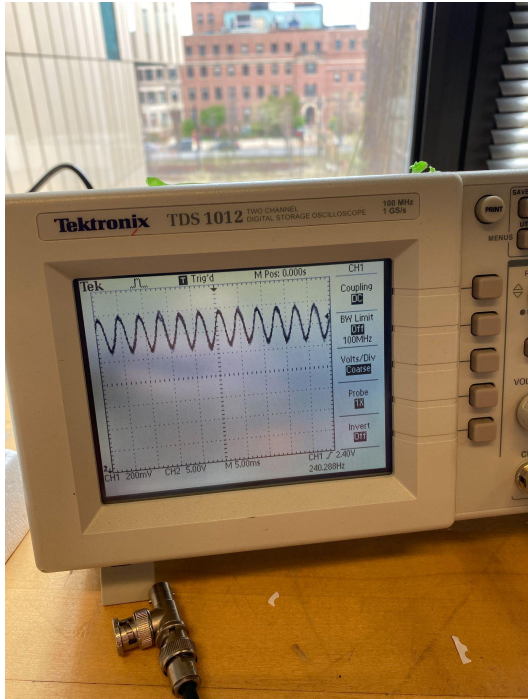
From actuator



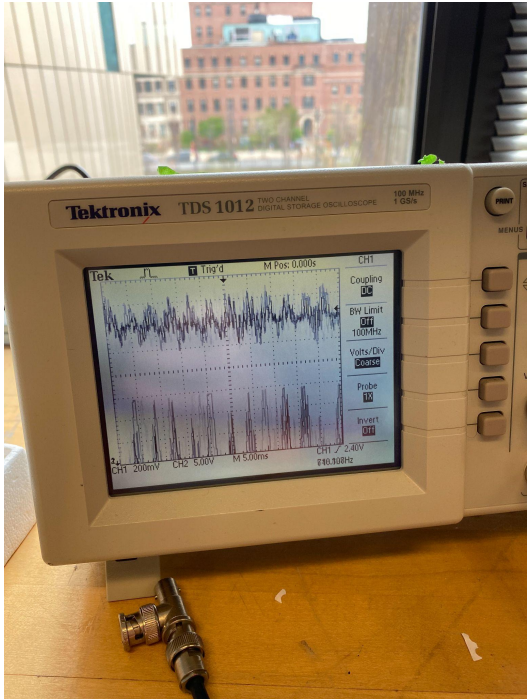
Frequency mismatch = Beats



Undamped



Damped



Issues

- Ambient vibrations too small to detect.
- Not all speaker signals produce measurable vibrations, resonance of stage?
- Hard to make quality and variable actuator signals.